

# Detailed proofs of theorems 1 and 2 given in [1]

Habti Abeida and Jean Pierre Delmas

## I. BACKGROUND

### A. Relations

We will make frequent use of the following well known relations which hold for any conformable matrices  $\mathbf{A}$ ,  $\mathbf{B}$ ,  $\mathbf{C}$  and  $\mathbf{D}$ .

$$\text{vec}(\mathbf{ABC}) = (\mathbf{C}^T \otimes \mathbf{A})\text{vec}(\mathbf{B}), \quad (1)$$

$$(\mathbf{A} \otimes \mathbf{B})(\mathbf{C} \otimes \mathbf{D}) = \mathbf{AC} \otimes \mathbf{BD}, \quad (2)$$

$$\text{Tr}(\mathbf{AB}) = (\text{vec}(\mathbf{A}^H))^H \text{vec}(\mathbf{B}). \quad (3)$$

### B. General expression of the CRB

The stochastic CRB is writing through the compact expression of the FIM:

$$\text{CRB}_{\text{sto}}^{-1}(\boldsymbol{\alpha}) = \frac{T}{2} \left( \frac{\partial \mathbf{r}_{\tilde{y}}}{\partial \boldsymbol{\alpha}^T} \right)^H \left( \mathbf{R}_{\tilde{y}}^{-T} \otimes \mathbf{R}_{\tilde{y}}^{-1} \right) \left( \frac{\partial \mathbf{r}_{\tilde{y}}}{\partial \boldsymbol{\alpha}^T} \right), \quad (4)$$

where the vectorization of  $\mathbf{R}_{\tilde{y}} = \tilde{\mathbf{A}}\mathbf{R}_s\tilde{\mathbf{A}}^H + \sigma_n^2\mathbf{I}$  is given from (1) by

$$\mathbf{r}_{\tilde{y}} \stackrel{\text{def}}{=} \text{vec}(\mathbf{R}_{\tilde{y}}) = (\tilde{\mathbf{A}}^* \otimes \tilde{\mathbf{A}})\text{vec}(\mathbf{R}_s) + \sigma_n^2 \text{vec}(\mathbf{I}).$$

To begin the proofs of the two theorems, all the first steps of [17] apply. In particular, using the partition

$$(\mathbf{R}_{\tilde{y}}^{-T/2} \otimes \mathbf{R}_{\tilde{y}}^{-1/2}) \left( \frac{\partial \mathbf{r}_{\tilde{y}}}{\partial \boldsymbol{\omega}^T} \middle| \frac{\partial \mathbf{r}_{\tilde{y}}}{\partial \boldsymbol{\rho}^T}, \frac{\partial \mathbf{r}_{\tilde{y}}}{\partial \sigma_n^2} \right) \stackrel{\text{def}}{=} (\mathbf{G} | \mathbf{V}, \mathbf{u}), \quad (5)$$

we can deduce from (4)

$$\frac{2}{T} \text{CRB}_{\text{sto}}^{-1}(\boldsymbol{\omega}) = \mathbf{G}^H \boldsymbol{\Pi}_{\Delta}^{\perp} \mathbf{G}, \quad (6)$$

with  $\Delta \stackrel{\text{def}}{=} (\mathbf{V}, \mathbf{u})$  and  $\boldsymbol{\Pi}_{\Delta}^{\perp} \stackrel{\text{def}}{=} \mathbf{I} - \boldsymbol{\Pi}_{\Delta}$ , where  $\boldsymbol{\Pi}_{\Delta}$  denotes the orthonormal projector on the columns of  $\Delta$ . Following [17, rel.(14)], it has been proved that

$$\boldsymbol{\Pi}_{\Delta}^{\perp} = \boldsymbol{\Pi}_{\mathbf{V}}^{\perp} - \frac{\boldsymbol{\Pi}_{\mathbf{V}}^{\perp} \mathbf{u} \mathbf{u}^H \boldsymbol{\Pi}_{\mathbf{V}}^{\perp}}{\mathbf{u}^H \boldsymbol{\Pi}_{\mathbf{V}}^{\perp} \mathbf{u}}, \quad (7)$$

where  $\frac{d\mathbf{r}_{\tilde{y}}}{d\sigma_n^2} = \text{vec}(\mathbf{I})$  implies by using (1), that

$$\mathbf{u} = (\mathbf{R}_{\tilde{y}}^{-T/2} \otimes \mathbf{R}_{\tilde{y}}^{-1/2})\text{vec}(\mathbf{I}) = \text{vec}(\mathbf{R}_{\tilde{y}}^{-1}). \quad (8)$$

Consequently using (6) and (7), if  $\mathbf{g}_k$  denotes the  $k$ -th column of  $\mathbf{G}$ , the  $(k, l)$  element of  $\frac{2}{T} \text{CRB}_{\text{sto}}^{-1}(\boldsymbol{\omega})$  can be written elementwise as

$$\frac{2}{T} [\text{CRB}_{\text{sto}}^{-1}(\boldsymbol{\omega})]_{k,l} = \mathbf{g}_k^H \boldsymbol{\Pi}_{\mathbf{V}}^{\perp} \mathbf{g}_l - \frac{\mathbf{g}_k^H \boldsymbol{\Pi}_{\mathbf{V}}^{\perp} \mathbf{u} \mathbf{u}^H \boldsymbol{\Pi}_{\mathbf{V}}^{\perp} \mathbf{g}_l}{\mathbf{u}^H \boldsymbol{\Pi}_{\mathbf{V}}^{\perp} \mathbf{u}}. \quad (9)$$

To proceed, we need to determine the expressions of  $\boldsymbol{\Pi}_{\mathbf{V}}^{\perp}$  associated with the two parametrizations of the real symmetric matrix  $\mathbf{R}_s$ . But as the steps of the proof given in [17] do not apply, we have to elaborate a little bit.

## II. PROOF OF THEOREM 1

For arbitrary real symmetric matrix  $\mathbf{R}_s$ , let  $\mathbf{r}_{s,k}$  denote the  $k$ th column of  $\mathbf{R}_s$ . We get from  $\mathbf{R}_{\tilde{y}} \stackrel{\text{def}}{=} E(\tilde{\mathbf{y}}_t \tilde{\mathbf{y}}_t^H) = \tilde{\mathbf{A}} \mathbf{R}_s \tilde{\mathbf{A}}^H + \sigma_n^2 \mathbf{I}$ ,

$$\begin{aligned} \frac{d\mathbf{R}_{\tilde{y}}}{d\omega_k} &= \left( \mathbf{0}, \dots, \tilde{\mathbf{a}}'_k, \dots, \mathbf{0} \right) \mathbf{R}_s \tilde{\mathbf{A}}^H + \tilde{\mathbf{A}} \mathbf{R}_s \begin{pmatrix} \mathbf{0}^T \\ \vdots \\ \tilde{\mathbf{a}}'_k{}^H \\ \vdots \\ \mathbf{0}^T \end{pmatrix} \\ &= \tilde{\mathbf{a}}'_k \mathbf{r}_{s,k}^T \tilde{\mathbf{A}}^H + \tilde{\mathbf{A}} \mathbf{r}_{s,k} \tilde{\mathbf{a}}'_k{}^H. \end{aligned}$$

where  $\tilde{\mathbf{a}}'_k \stackrel{\text{def}}{=} d\tilde{\mathbf{a}}_k/d\omega_k$ . Hence using (1), the  $k$ th column of  $\mathbf{G}$  in (5) is given by

$$\mathbf{g}_k = (\mathbf{R}_{\tilde{y}}^{-T/2} \otimes \mathbf{R}_{\tilde{y}}^{-1/2}) \text{vec} \left( \frac{d\mathbf{R}_{\tilde{y}}}{d\omega_k} \right) = \text{vec} \left( \mathbf{R}_{\tilde{y}}^{-1/2} \frac{d\mathbf{R}_{\tilde{y}}}{d\omega_k} \mathbf{R}_{\tilde{y}}^{-1/2} \right) = \text{vec}(\mathbf{Z}_k^H + \mathbf{Z}_k), \quad (10)$$

where

$$\mathbf{Z}_k \stackrel{\text{def}}{=} \mathbf{R}_{\tilde{y}}^{-1/2} \tilde{\mathbf{A}} \mathbf{r}_{s,k} \tilde{\mathbf{a}}'_k{}^H \mathbf{R}_{\tilde{y}}^{-1/2}. \quad (11)$$

Next, we determine  $\mathbf{V}$ . The key observation to note here, is that the real-valued symmetric matrix  $\mathbf{R}_s$ , using [20, rel.(7.18)], can be written as

$$\text{vec}(\mathbf{R}_s) = \mathbf{D}_K \boldsymbol{\rho},$$

where  $\mathbf{D}_K$  is the so-called duplication matrix, and hence from (5)

$$\mathbf{V} = (\mathbf{R}_{\tilde{y}}^{-T/2} \tilde{\mathbf{A}}^* \otimes \mathbf{R}_{\tilde{y}}^{-1/2} \tilde{\mathbf{A}}) \mathbf{D}_K \stackrel{\text{def}}{=} \mathbf{W} \mathbf{D}_K, \quad (12)$$

and consequently:

$$\begin{aligned} \mathbf{\Pi}_{\mathbf{V}}^\perp &= \mathbf{I} - \mathbf{V}(\mathbf{V}^H \mathbf{V})^{-1} \mathbf{V}^H = \mathbf{I} - \mathbf{W} \mathbf{D}_K (\mathbf{D}_K^T \mathbf{W}^H \mathbf{W} \mathbf{D}_K)^{-1} \mathbf{D}_K^T \mathbf{W}^H \\ &= \mathbf{I} - \mathbf{W} \mathbf{D}_K (\mathbf{D}_K^T (\mathbf{U} \otimes \mathbf{U}) \mathbf{D}_K)^{-1} \mathbf{D}_K^T \mathbf{W}^H, \end{aligned} \quad (13)$$

using

$$\mathbf{W}^H \mathbf{W} = (\tilde{\mathbf{A}}^T \mathbf{R}_{\tilde{y}}^{-T} \tilde{\mathbf{A}}^*) \otimes (\tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{y}}^{-1} \tilde{\mathbf{A}}) \stackrel{\text{def}}{=} \mathbf{U} \otimes \mathbf{U},$$

deduced from (2), where

$$\mathbf{U} \stackrel{\text{def}}{=} \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{y}}^{-1} \tilde{\mathbf{A}} \quad (14)$$

is an  $K \times K$  real symmetric non-singular matrix. Then it follows from [20, Theorem 7.38], and some simple algebraic manipulations using [20, Theorem 7.37, rel.(c)] and [20, Theorem 7.34, rel.(d)], that (13) becomes

$$\mathbf{\Pi}_{\mathbf{V}}^\perp = \mathbf{I} - \mathbf{W}(\mathbf{U}^{-1} \otimes \mathbf{U}^{-1}) \mathbf{W}^H. \quad (15)$$

Now let us prove that  $\mathbf{u}^H \mathbf{\Pi}_{\mathbf{V}}^\perp \mathbf{g}_k = 0$ .

Using the formula (1), we get from (11)

$$\begin{aligned} \mathbf{W}^H \mathbf{g}_k &= (\tilde{\mathbf{A}}^T \mathbf{R}_{\tilde{y}}^{-T/2} \otimes \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{y}}^{-1/2}) \text{vec}(\mathbf{Z}_k^H + \mathbf{Z}_k) \\ &= \text{vec}(\tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{y}}^{-1/2} \mathbf{Z}_k^H \mathbf{R}_{\tilde{y}}^{-1/2} \tilde{\mathbf{A}}) + \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{y}}^{-1/2} \mathbf{Z}_k \mathbf{R}_{\tilde{y}}^{-1/2} \tilde{\mathbf{A}} \\ &= \text{vec}(\mathbf{b}_k \mathbf{c}_k^T + \mathbf{c}_k \mathbf{b}_k^T) \stackrel{\text{def}}{=} \text{vec}(\mathbf{H}_k), \end{aligned} \quad (16)$$

where  $\mathbf{b}_k$  and  $\mathbf{c}_k$  are the  $K \times 1$  real-valued vectors given by

$$\mathbf{b}_k^T \stackrel{\text{def}}{=} \tilde{\mathbf{a}}'_k{}^H \mathbf{R}_{\tilde{y}}^{-1} \tilde{\mathbf{A}} \quad \text{and} \quad \mathbf{c}_k \stackrel{\text{def}}{=} \mathbf{U} \mathbf{r}_{s,k}. \quad (17)$$

From (10), (13) and (16) we obtain

$$\begin{aligned}
\Pi_{\mathbf{V}}^{\perp} \mathbf{g}_k &= \mathbf{g}_k - \mathbf{W}(\mathbf{U}^{-1} \otimes \mathbf{U}^{-1}) \mathbf{W}^H \mathbf{g}_k \\
&= \mathbf{g}_k - \mathbf{W}(\mathbf{U}^{-1} \otimes \mathbf{U}^{-1}) \text{vec}(\mathbf{H}_k) \\
&= \mathbf{g}_k - \text{vec}(\mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2} \tilde{\mathbf{A}} \mathbf{U}^{-1} \mathbf{H}_k \mathbf{U}^{-1} \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2}) \\
&= \mathbf{g}_k - \text{vec}(\mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2} \tilde{\mathbf{A}} \mathbf{U}^{-1} (\mathbf{b}_k \mathbf{c}_k^T + \mathbf{c}_k \mathbf{b}_k^T) \mathbf{U}^{-1} \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2}) \\
&= \mathbf{g}_k - \text{vec}(\mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2} \tilde{\mathbf{A}} \mathbf{U}^{-1} \mathbf{b}_k \mathbf{c}_k^T \mathbf{U}^{-1} \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2} + \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2} \tilde{\mathbf{A}} \mathbf{U}^{-1} \mathbf{c}_k \mathbf{b}_k^T \mathbf{U}^{-1} \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2}). \tag{18}
\end{aligned}$$

To simplify the expression (18), we need the following equality (19)

$$\begin{aligned}
\tilde{\mathbf{A}} \mathbf{U}^{-1} \tilde{\mathbf{A}}^H &= \tilde{\mathbf{A}} (\tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{\mathbf{y}}}^{-1} \tilde{\mathbf{A}})^{-1} \tilde{\mathbf{A}}^H \\
&= \tilde{\mathbf{A}} (\tilde{\mathbf{A}}^H \tilde{\mathbf{A}})^{-1} (\tilde{\mathbf{A}}^H \tilde{\mathbf{A}} \mathbf{R}_s + \sigma_n^2 \mathbf{I}) \tilde{\mathbf{A}}^H \\
&= \tilde{\mathbf{A}} \mathbf{R}_s \tilde{\mathbf{A}}^H + \sigma_n^2 \Pi_{\tilde{\mathbf{A}}} \\
&= \Pi_{\tilde{\mathbf{A}}} \mathbf{R}_{\tilde{\mathbf{y}}}, \tag{19}
\end{aligned}$$

where  $\Pi_{\tilde{\mathbf{A}}} \stackrel{\text{def}}{=} \tilde{\mathbf{A}} (\tilde{\mathbf{A}}^H \tilde{\mathbf{A}})^{-1} \tilde{\mathbf{A}}^H$ . Using  $\mathbf{b}_k^T \mathbf{U}^{-1} \tilde{\mathbf{A}}^H = \tilde{\mathbf{a}}_k'^H \Pi_{\tilde{\mathbf{A}}}$  and  $\mathbf{U}^{-1} \mathbf{c}_k = \mathbf{r}_{s,k}$  deduced from (19) and (17), (18) can be simplified as

$$\begin{aligned}
\Pi_{\mathbf{V}}^{\perp} \mathbf{g}_k &= \mathbf{g}_k - \text{vec}(\mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2} \tilde{\mathbf{A}} \mathbf{r}_{s,k} \tilde{\mathbf{a}}_k'^H \Pi_{\tilde{\mathbf{A}}} \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2} + \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2} \Pi_{\tilde{\mathbf{A}}} \tilde{\mathbf{a}}_k' \mathbf{r}_{s,k}^T \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2}) \\
&= \mathbf{g}_k - \text{vec}(\mathbf{Y}_k + \mathbf{Y}_k^H) = \text{vec}(\mathbf{Z}_k - \mathbf{Y}_k + \mathbf{Z}_k^H - \mathbf{Y}_k^H) \tag{20}
\end{aligned}$$

where  $\mathbf{Y}_k \stackrel{\text{def}}{=} \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2} \tilde{\mathbf{A}} \mathbf{r}_{s,k} \tilde{\mathbf{a}}_k'^H \Pi_{\tilde{\mathbf{A}}} \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2}$ . From (20) and (8) together with the identity (3), we get

$$\begin{aligned}
\mathbf{u}^H \Pi_{\mathbf{V}}^{\perp} \mathbf{g}_k &= (\text{vec}(\mathbf{R}_{\tilde{\mathbf{y}}}^{-1}))^H \text{vec}(\mathbf{Z}_k - \mathbf{Y}_k + \mathbf{Z}_k^H - \mathbf{Y}_k^H) \\
&= \text{Tr}(\mathbf{R}_{\tilde{\mathbf{y}}}^{-1} (\mathbf{Z}_k - \mathbf{Y}_k + \mathbf{Z}_k^H - \mathbf{Y}_k^H)) \\
&= \text{Tr}(\mathbf{R}_{\tilde{\mathbf{y}}}^{-1} (\mathbf{Z}_k - \mathbf{Y}_k)) + \text{Tr}((\mathbf{Z}_k^H - \mathbf{Y}_k^H) \mathbf{R}_{\tilde{\mathbf{y}}}^{-1}) \\
&\stackrel{\text{def}}{=} \text{Tr}(\mathbf{F}_k) + \text{Tr}(\mathbf{F}_k^H). \tag{21}
\end{aligned}$$

Let us now prove that

$$\text{Tr}(\mathbf{F}_k) = 0.$$

After replacing  $\mathbf{Z}_k$  and  $\mathbf{Y}_k$  by their expression, we obtain

$$\mathbf{Z}_k - \mathbf{Y}_k = \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2} \tilde{\mathbf{A}} \mathbf{r}_{s,k} \tilde{\mathbf{a}}_k'^H \Pi_{\tilde{\mathbf{A}}}^{\perp} \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2}. \tag{22}$$

Thus

$$\text{Tr}(\mathbf{F}_k) = \text{Tr}(\mathbf{r}_{s,k} \tilde{\mathbf{a}}_k'^H \Pi_{\tilde{\mathbf{A}}}^{\perp} \mathbf{R}_{\tilde{\mathbf{y}}}^{-2} \tilde{\mathbf{A}}). \tag{23}$$

Since

$$\Pi_{\tilde{\mathbf{A}}}^{\perp} \mathbf{R}_{\tilde{\mathbf{y}}} = \sigma_n^2 \Pi_{\tilde{\mathbf{A}}}^{\perp} \text{ or equivalently } \Pi_{\tilde{\mathbf{A}}}^{\perp} \mathbf{R}_{\tilde{\mathbf{y}}}^{-1} = \frac{1}{\sigma_n^2} \Pi_{\tilde{\mathbf{A}}}^{\perp}, \tag{24}$$

we get

$$\Pi_{\tilde{\mathbf{A}}}^{\perp} \mathbf{R}_{\tilde{\mathbf{y}}}^{-2} \tilde{\mathbf{A}} = \left( \frac{1}{\sigma_n^2} \Pi_{\tilde{\mathbf{A}}}^{\perp} \right) (\mathbf{R}_{\tilde{\mathbf{y}}}^{-1} \tilde{\mathbf{A}}) = \frac{1}{\sigma_n^4} \Pi_{\tilde{\mathbf{A}}}^{\perp} \tilde{\mathbf{A}} = \mathbf{O}, \tag{25}$$

and thus from (23), we get  $\text{Tr}(\mathbf{F}_k) = 0$ . It follows then from (21) that  $\mathbf{u}^H \Pi_{\mathbf{V}}^{\perp} \mathbf{g}_k = 0$ . ■

This identity, together with (10) and (20) allows us to simplify (9) as

$$\begin{aligned}
\frac{2}{T} [\text{CRB}_{\text{sto}}^{-1}(\boldsymbol{\omega})]_{k,l} &= \mathbf{g}_k^H \Pi_{\mathbf{V}}^{\perp} \mathbf{g}_l \\
&= (\text{vec}(\mathbf{Z}_k^H + \mathbf{Z}_k))^H \text{vec}(\mathbf{Z}_l - \mathbf{Y}_l + \mathbf{Z}_l^H - \mathbf{Y}_l^H) \\
&= 2\text{Re}(\text{Tr}((\mathbf{Z}_k + \mathbf{Z}_k^H)(\mathbf{Z}_l - \mathbf{Y}_l))). \tag{26}
\end{aligned}$$

Note from (11) and (22) that

$$\text{Tr}(\mathbf{Z}_k^H(\mathbf{Z}_l - \mathbf{Y}_l)) = (\tilde{\mathbf{a}}_l'^H \mathbf{\Pi}_{\tilde{\mathbf{A}}}^\perp \mathbf{R}_{\tilde{\mathbf{y}}}^{-1} \tilde{\mathbf{a}}_k'^H)(\mathbf{r}_{s,k}^T \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{\mathbf{y}}}^{-1} \tilde{\mathbf{A}} \mathbf{r}_{s,l}).$$

Using (24), we get

$$\text{Tr}(\mathbf{Z}_k^H(\mathbf{Z}_l - \mathbf{Y}_l)) = \frac{1}{\sigma_n^2} (\tilde{\mathbf{a}}_l'^H \mathbf{\Pi}_{\tilde{\mathbf{A}}}^\perp \tilde{\mathbf{a}}_k'^H)(\mathbf{r}_{s,k}^T \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{\mathbf{y}}}^{-1} \tilde{\mathbf{A}} \mathbf{r}_{s,l}), \quad (27)$$

and

$$\begin{aligned} \text{Tr}(\mathbf{Z}_k(\mathbf{Z}_l - \mathbf{Y}_l)) &= (\tilde{\mathbf{a}}_k'^H \mathbf{R}_{\tilde{\mathbf{y}}}^{-1} \tilde{\mathbf{A}} \mathbf{r}_{s,l})(\tilde{\mathbf{a}}_l'^H \mathbf{\Pi}_{\tilde{\mathbf{A}}}^\perp \mathbf{R}_{\tilde{\mathbf{y}}}^{-1} \tilde{\mathbf{A}} \mathbf{r}_{s,k}) \\ &= \frac{1}{\sigma_n^2} (\tilde{\mathbf{a}}_k'^H \mathbf{R}_{\tilde{\mathbf{y}}}^{-1} \tilde{\mathbf{A}} \mathbf{r}_{s,l})(\tilde{\mathbf{a}}_l'^H \mathbf{\Pi}_{\tilde{\mathbf{A}}}^\perp \tilde{\mathbf{A}} \mathbf{r}_{s,k}) = 0. \end{aligned} \quad (28)$$

It follows then from (27) and (28) that (26) can be simplified as

$$[\text{CRB}_{\text{sto}}^{-1}(\boldsymbol{\omega})]_{k,l} = \frac{T}{\sigma_n^2} \text{Re} \left( (\tilde{\mathbf{a}}_k'^H \mathbf{\Pi}_{\tilde{\mathbf{A}}}^\perp \tilde{\mathbf{a}}_l') (\mathbf{r}_{s,k}^T \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{\mathbf{y}}}^{-1} \tilde{\mathbf{A}} \mathbf{r}_{s,l}) \right). \quad (29)$$

Finally, writing (29) in matrix form, theorem 1 is proved.

### III. PROOF OF THEOREM 2

For coherent sources for which  $\mathbf{R}_s = \mathbf{c}\mathbf{c}^T$  and  $\boldsymbol{\rho} = \mathbf{c}$ , we follow the steps similar to those in the proof of theorem 1. First, we note that the  $k$ -th columns of  $\mathbf{G}$  are still given by (10), but with now

$$\mathbf{z}_k = c_k \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2} \tilde{\mathbf{A}} \mathbf{c} \tilde{\mathbf{a}}_k'^H \mathbf{R}_{\tilde{\mathbf{y}}}^{-1/2}. \quad (30)$$

Second,  $\text{vec}(\mathbf{R}_s) = \mathbf{c} \otimes \mathbf{c}$  implies that

$$\frac{\partial \text{vec}(\mathbf{R}_s)}{\partial \mathbf{c}^T} = \mathbf{c} \otimes \mathbf{I} + \mathbf{I} \otimes \mathbf{c} = 2\mathbf{N}_K(\mathbf{c} \otimes \mathbf{I}), \quad (31)$$

where  $\mathbf{N}_K$  is the  $K \times K$  matrix defined in [20, Theorem 7.34]. Consequently (12) becomes

$$\mathbf{V} = 2\mathbf{W}\mathbf{N}_K(\mathbf{c} \otimes \mathbf{I}), \quad (32)$$

which gives after some algebraic manipulation using [20, Theorem 7.34, rel.(d)]:

$$\mathbf{\Pi}_{\tilde{\mathbf{V}}}^\perp \stackrel{\text{def}}{=} \mathbf{I} - \mathbf{V}(\mathbf{V}^H \mathbf{V})^{-1} \mathbf{V}^H = \mathbf{I} - \mathbf{V}_1 \bar{\mathbf{V}}^{-1} \mathbf{V}_1^H, \quad (33)$$

with  $\mathbf{V}_1 \stackrel{\text{def}}{=} \mathbf{W}\mathbf{N}_K(\mathbf{c} \otimes \mathbf{I})$  and  $\bar{\mathbf{V}} \stackrel{\text{def}}{=} (\mathbf{c}^T \otimes \mathbf{I})\mathbf{N}_K(\mathbf{U} \otimes \mathbf{U})\mathbf{N}_K(\mathbf{c} \otimes \mathbf{I})$  where  $\mathbf{U}$  is defined by (14).  $\bar{\mathbf{V}}$  can be simplified as

$$\begin{aligned} \bar{\mathbf{V}} &= (\mathbf{c}^T \otimes \mathbf{I})\mathbf{N}_K(\mathbf{U} \otimes \mathbf{U})(\mathbf{c} \otimes \mathbf{I}) \\ &= (\mathbf{c}^T \otimes \mathbf{I})\mathbf{N}_K(\mathbf{U}\mathbf{c} \otimes \mathbf{U}) \\ &= \frac{1}{2} (\kappa_c \mathbf{U} + \mathbf{U}\mathbf{c}\mathbf{c}^T \mathbf{U}^T), \end{aligned} \quad (34)$$

where the first equality follows from [20, Theorem 7.35, rel.(a)] and the third equality follows from [20, Theorem 7.31, rel.(d)] using the definition of  $\mathbf{N}_K$  [20, Theorem 7.34] and  $\kappa_c \stackrel{\text{def}}{=} \mathbf{c}^T \mathbf{U} \mathbf{c}$ . The inverse  $\bar{\mathbf{V}}^{-1}$  is deduced from the matrix inversion lemma applied to (34)

$$\bar{\mathbf{V}}^{-1} = \frac{2}{\kappa_c} \left( \mathbf{U}^{-1} - \frac{1}{2\kappa_c} \mathbf{c}\mathbf{c}^T \right). \quad (35)$$

Now let us prove that  $\mathbf{u}^H \mathbf{\Pi}_{\tilde{\mathbf{V}}}^\perp \mathbf{g}_k = 0$ .

Using  $\bar{\mathbf{U}} \stackrel{\text{def}}{=} \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{y}}^{-2} \tilde{\mathbf{A}}$  as a real-valued symmetric matrix and the identity (1), we get

$$\begin{aligned} \mathbf{u}^H \mathbf{V}_1 &= (\text{vec}(\mathbf{R}_{\tilde{y}}^{-1}))^H (\mathbf{R}_{\tilde{y}}^{-T/2} \tilde{\mathbf{A}}^* \otimes \mathbf{R}_{\tilde{y}}^{-1/2} \tilde{\mathbf{A}}) \mathbf{N}_K (\mathbf{c} \otimes \mathbf{I}) \\ &= (\text{vec}(\bar{\mathbf{U}}))^T (\mathbf{c} \otimes \mathbf{I}) \\ &= \mathbf{c}^T \bar{\mathbf{U}}, \end{aligned} \quad (36)$$

where the second equality follows from [20, Theorem 7.34, rel.(c)] and the third equality uses (1). Furthermore:

$$\begin{aligned} \mathbf{V}_1^H \mathbf{g}_k &= (\mathbf{c}^T \otimes \mathbf{I}) \mathbf{N}_K^T \mathbf{W}^H \mathbf{g}_k \\ &= c_k (\mathbf{c}^T \otimes \mathbf{I}) \mathbf{N}_K^T \text{vec}(\mathbf{b}_k \mathbf{c}^T \mathbf{U}^T + \mathbf{U} \mathbf{c} \mathbf{b}_k^T) \\ &= c_k (\mathbf{c}^T \otimes \mathbf{I}) \text{vec}(\mathbf{b}_k \mathbf{c}^T \mathbf{U}^T + \mathbf{U} \mathbf{c} \mathbf{b}_k^T) \\ &= c_k \left( \kappa_c \mathbf{b}_k + (\mathbf{b}_k^T \mathbf{c}) \mathbf{U} \mathbf{c} \right), \end{aligned} \quad (37)$$

where the second equality follows from  $\mathbf{W}^H \mathbf{g}_k = c_k \text{vec}(\mathbf{b}_k \mathbf{c}_k^T + \mathbf{c}_k \mathbf{b}_k^T)$  deduced from (16) with  $\mathbf{c}_k$  defined in (17) is now given by  $c_k \mathbf{U} \mathbf{c}$ , and the third equality follows from [20, Theorem 7.34, rel.(c)] and the property that  $\mathbf{b}_k \mathbf{c}^T \mathbf{U}^T + \mathbf{U} \mathbf{c} \mathbf{b}_k^T$  is a real-valued symmetric matrix. In similar way, we have

$$\mathbf{u}^H \mathbf{g}_k = 2c_k \tilde{\mathbf{a}}_k'^H \mathbf{R}_{\tilde{y}}^{-2} \tilde{\mathbf{A}} \mathbf{c}. \quad (38)$$

From (35) and (37), we get

$$\bar{\mathbf{V}}^{-1} \mathbf{V}_1^H \mathbf{g}_k = 2c_k \mathbf{U}^{-1} \mathbf{b}_k. \quad (39)$$

It follows from (33), (39), (36) and (38) that

$$\begin{aligned} \mathbf{u}^H \mathbf{\Pi}_{\bar{\mathbf{V}}}^\perp \mathbf{g}_k &= \mathbf{u}^H \mathbf{g}_k - \mathbf{u}^H \mathbf{V}_1 \bar{\mathbf{V}}^{-1} \mathbf{V}_1^H \mathbf{g}_k \\ &= 2c_k \tilde{\mathbf{a}}_k'^H \mathbf{R}_{\tilde{y}}^{-2} \tilde{\mathbf{A}} \mathbf{c} - 2c_k \mathbf{c}^T \bar{\mathbf{U}} \mathbf{U}^{-1} \mathbf{b}_k \\ &= 2c_k \tilde{\mathbf{a}}_k'^H \mathbf{R}_{\tilde{y}}^{-2} \tilde{\mathbf{A}} \mathbf{c} - 2c_k \mathbf{c}^T \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{y}}^{-2} \tilde{\mathbf{a}}_k' = 0, \end{aligned}$$

where the third equality follows from the identity  $\bar{\mathbf{U}} \mathbf{U}^{-1} \tilde{\mathbf{A}}^H = \tilde{\mathbf{A}}^H \mathbf{R}_{\tilde{y}}^{-1}$  obtained using (19) and (25) which is equivalent to  $\mathbf{R}_{\tilde{y}}^{-2} \tilde{\mathbf{A}} = \mathbf{\Pi}_{\tilde{\mathbf{A}}} \mathbf{R}_{\tilde{y}}^{-2} \tilde{\mathbf{A}}$ . ■

It follows that the elements of (6) reduce to

$$\frac{2}{T} [\text{CRB}_{\text{sto}}^{-1}(\boldsymbol{\omega})]_{k,l} = \mathbf{g}_k^H \mathbf{\Pi}_{\bar{\mathbf{V}}}^\perp \mathbf{g}_l = \mathbf{g}_k^H \mathbf{g}_l - \mathbf{g}_k^H \mathbf{V}_1 \bar{\mathbf{V}}^{-1} \mathbf{V}_1^H \mathbf{g}_l, \quad (40)$$

where we get

$$\begin{aligned} \mathbf{g}_k^H \mathbf{g}_l &= \text{vec}(\mathbf{Z}_k^H + \mathbf{Z}_k)^H \text{vec}(\mathbf{Z}_l^H + \mathbf{Z}_l) \\ &= \text{Tr}[(\mathbf{Z}_k^H + \mathbf{Z}_k)^H (\mathbf{Z}_l^H + \mathbf{Z}_l)] \\ &= 2c_k c_l \left( \kappa_c \tilde{\mathbf{a}}_k'^H \mathbf{R}_{\tilde{y}}^{-1} \tilde{\mathbf{a}}_l' + (\mathbf{b}_k^T \mathbf{c})(\mathbf{b}_l^T \mathbf{c}) \right), \end{aligned} \quad (41)$$

where the first equality is deduced from the definition (10) of  $\mathbf{g}_k$  associated with (30), the second equality follows from the identity (3), and the third equality follows from the definition (17) of  $\mathbf{b}_k$  and the property that  $\tilde{\mathbf{a}}_k'^H \mathbf{R}_{\tilde{y}}^{-1} \tilde{\mathbf{a}}_l'$  is real-valued. On the other hand, we get

$$\begin{aligned} \mathbf{g}_k^H \mathbf{V}_1 \bar{\mathbf{V}}^{-1} \mathbf{V}_1^H \mathbf{g}_l &= 2c_k c_l (\mathbf{b}_k^T \mathbf{U}^{-1}) (\kappa_c \mathbf{b}_l + (\mathbf{b}_l^T \mathbf{c}) \mathbf{U} \mathbf{c}) \\ &= 2c_k c_l \left( \kappa_c \tilde{\mathbf{a}}_k'^H \mathbf{R}_{\tilde{y}}^{-1} \mathbf{\Pi}_{\tilde{\mathbf{A}}} \tilde{\mathbf{a}}_l' + (\mathbf{b}_k^T \mathbf{c})(\mathbf{b}_l^T \mathbf{c}) \right), \end{aligned} \quad (42)$$

where the first equality follows from (37) and (39) and the second equality is deduced from (19). Plugging (41) and (42) into (40), we get:

$$\frac{2}{T} [\text{CRB}_{\text{sto}}^{-1}(\boldsymbol{\omega})]_{k,l} = \frac{2\kappa_c}{\sigma_n^2} c_k c_l (\tilde{\mathbf{a}}_k'^H \mathbf{\Pi}_{\tilde{\mathbf{A}}}^\perp \tilde{\mathbf{a}}_l'),$$

using  $\mathbf{R}_{\tilde{y}}^{-1} \mathbf{\Pi}_{\tilde{\mathbf{A}}}^\perp = \frac{1}{\sigma_n^2} \mathbf{\Pi}_{\tilde{\mathbf{A}}}^\perp$ . Finally, writing (40) in matrix form, theorem 2 is proved.

## REFERENCES

- [1] H. Abeida and J.P. Delmas, "Direct derivation of the stochastic CRB of DOA estimation for rectilinear sources," *IEEE Signal Processing letters*, vol. 24, no. 10, pp. 1522-1526, October 2017.
- [2] P. Gounon, C. Adnet, and J. Galy, "Localisation angulaire de signaux non circulaires," *Traitement du Signal*, vol. 15, no. 1, pp. 17-23, 1998.
- [3] H. Abeida and J.P. Delmas, "MUSIC-like estimation of direction of arrival for non-circular sources," *IEEE Trans. Signal Process.*, vol. 54, no. 7, pp. 2678-2690, July 2006.
- [4] P. Chargé, Y. Wang, and J. Saillard, "A non-circular sources direction finding method using polynomial rooting," *Signal Process.*, vol. 81, pp. 1765-1770, 2001.
- [5] A. Zoubir, P. Chargé, and Y. Wang, "Non circular sources localization with ESPRIT," in *Proc. Eur. Conf. Wireless Technology (ECWT)*, Munich, Germany, Oct. 2003.
- [6] M. Haardt and F. Roemer, "Enhancements of unitary esprit for noncircular sources," *Proc. ICASSP*, vol. 2, pp. 101-104, Montreal, QC, Canada, May 2004.
- [7] J. Steinwandt, F. Roemer, M. Haardt, and G. Del Galdo, "R-dimensional ESPRIT-type algorithms for strictly second-order non-circular sources and their performance analysis," *IEEE Trans. Signal Processing*, vol. 62, no. 18, pp. 4824-4838, Sept. 2014.
- [8] J.P. Delmas and H. Abeida, "Stochastic Cramer-Rao bound for non-circular signals with application to DOA estimation," *IEEE Trans. Signal Process.*, vol. 52, no. 11, pp. 3192-3199, Nov. 2004.
- [9] H. Abeida and J.P. Delmas, "Efficiency of subspace-based DOA estimators," *Signal Processing*, vol. 87, no. 9, pp. 2075-2084, Sept. 2007.
- [10] H. Abeida and J.P. Delmas, "Bornes de Cramer Rao déterministe et stochastique de DOA de signaux rectilignes non corrélés," *Proc. GRETSI*, Troyes, Sept. 2007, [http://documents.irevues.inist.fr/bitstream/handle/2042/17736/GRETSI\\_2007\\_1245.pdf?sequence=1](http://documents.irevues.inist.fr/bitstream/handle/2042/17736/GRETSI_2007_1245.pdf?sequence=1).
- [11] F. Roemer and M. Haardt, "Deterministic Cramer Rao bounds for strict sense noncircular sources," *Proc. Internat. ITG/IEEE Workshop on Smart Antennas (WSA'07)*, Vienne, Austria, Feb. 2007.
- [12] J. Steinwandt, F. Roemer, M. Haardt, and G. Del Galdo, "Deterministic Cramer-Rao bound for strictly non-circular sources and analytical analysis of the achievable gains," *IEEE Trans. Signal Process.*, vol. 64, no. 17, pp. 4417-4431, Sept. 2016.
- [13] D.T. Vu, A. Renaux, R. Boyer, and S. Marcos "Some results on the Weiss-Weinstein bound for conditional and unconditional signal models in array processing," *Signal Processing*, vol. 95, pp. 126-148, Feb. 2014.
- [14] P. Stoica and A. Nehorai, "Performance study of conditional and unconditional direction of arrival estimation," *IEEE Trans. Signal Process.*, vol. 38, no. 10, pp. 1783-1795, Oct. 1990.
- [15] D. Slepian, "Estimation of signal parameters in the presence of noise," in *Trans. IRE Prof. Grop Inform. Theory PG IT-3*, pp. 68-89, 1954.
- [16] W.J. Bangs "Array processing with generalized beamformers," *Ph.D. thesis Yale University, New Haven, CT*, 1971.
- [17] P. Stoica, A.G. Larsson, and A.B. Gershman, "The stochastic CRB for array processing: a textbook derivation," *IEEE Signal Process. letters*, vol. 8, no. 5, pp. 148-150, May 2001.
- [18] M. Jansson, B. Göransson, and B. Ottersten, "Subspace method for direction of arrival estimation of uncorrelated emitter signals," *IEEE Trans. Signal Process.*, vol. 47, no. 4, pp. 945-956, April 1999.
- [19] J. Sheinvald, M. Wax, and A.J. Weiss, "On maximum-likelihood localization of coherent signals," *IEEE Transactions on Signal Processing*, vol. 44, no. 10, pp. 2475-2482, Oct. 1996.
- [20] J. R. Schott, *Matrix analysis for statistics*, Wiley, New York, 1997.
- [21] P. Stoica and R. Moses, *Spectral analysis of signals*, Prentice-Hall, Upper Saddle River, NJ, 2005.
- [22] P. Stoica and A. Nehorai, "MUSIC, maximum likelihood, and Cramer-Rao bound: Further results and comparisons," *IEEE Trans. Signal Process.*, vol. 38, no. 12, pp. 2140-2150, Dec. 1990.
- [23] R.A. Horn and C.R. Johnson, *Matrix analysis*, Cambridge University Press, 1996.