

## Asymptotic Normality of Sample Covariance Matrix for Mixed Spectra Time Series: Application to Sinusoidal Frequencies Estimation

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**Abstract**—This correspondence addresses the asymptotic normal distribution of the sample mean and the sample covariance matrix of mixed spectra time series containing a sum of sinusoids and a moving average (MA) process. Two central limit (CL) theorems are proved. As an application of this result, the asymptotic normal distribution of any sinusoidal frequencies estimator of such time series based on second-order statistics is deduced.

**Index Terms**—Central limit (CL) theorem, covariance-based sinusoidal frequencies estimation, mixed spectra time series, sample covariance matrix.

### I. INTRODUCTION

There is considerable literature (e.g., [1]–[4]) concerning the asymptotic Gaussian distribution of the sample mean and the sample covariance matrix of the real-valued stationary processes  $x_t$ . Several situations have been considered, among them when  $x_t$  is a generalized linear process, satisfies mixing conditions, or is Gaussian with a power spectral density. However, few contributions have been devoted to the asymptotic distributions of the sample covariance matrix associated with mixed spectra time series. Subsequent to the revision of this manuscript, [5] was brought to our attention, where this problem is tackled with quite advanced statistical tools such as martingale theory.

We will be concerned with real- or complex-valued<sup>1</sup> processes of the type

$$x_t = m + \sum_{k=1}^K a_k \cos(2\pi f_k t + \phi_k) + v_t$$

$$\text{or } x_t = m + \sum_{k=1}^K a_k e^{i\phi_k} e^{i2\pi f_k t} + v_t \quad (1.1)$$

with

$$v_t = \sum_{q=0}^Q b_q u_{t-q}. \quad (1.2)$$

Throughout this correspondence,  $(u_t)_{t=1, \dots, n}$  is a sequence of zero-mean independent and identically distributed (i.i.d.) random variables where  $E|u_t^4| < \infty$ , with

$$c_u \stackrel{\text{def}}{=} E(u_t^2), \quad \kappa_u \stackrel{\text{def}}{=} \text{Cum}(u_t, u_t, u_t, u_t)$$

and

$$c_u \stackrel{\text{def}}{=} E|u_t^2|, \quad c'_u \stackrel{\text{def}}{=} E(u_t^2)$$

$$\kappa_u \stackrel{\text{def}}{=} \text{Cum}(u_t, u_t^*, u_t, u_t^*)$$

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<sup>1</sup>Complex processes appear as complex envelope of bandpass real processes.

respectively in the real and the possibly noncircular<sup>2</sup> complex case.  $(a_k)_{k=1, \dots, K}$  and  $(b_q)_{q=0, \dots, Q}$  are unknown fixed real or complex numbers, respectively.  $m$  is an unknown fixed number and  $f_k$  are unknown fixed distinct real numbers in  $]0, 1/2[$  for real-valued processes [resp., in  $]0, 1/2[$  for complex-valued processes]. For the phases  $\phi_k$ , the model (1.1) can be interpreted in two different ways, leading to different statistical descriptions.

- 1) We can assume that  $\phi_k$  are random variables uniformly distributed on  $[0, 2\pi]$  and that  $(\phi_k)_{k=1, \dots, K}$  and  $u_t$  are mutually independent. In this case,  $x_t$  is a wide-sense-stationary process.
- 2) We can assume that  $\phi_k$  are nonrandom unknown parameters<sup>3</sup> and so  $x_t$  is not a wide-sense-stationary process.

We are interested in the asymptotic distribution of the sample mean  $m_n \stackrel{\text{def}}{=} \frac{1}{n} \sum_{t=1}^n x_t$  and of the sample covariance matrix

$$\mathbf{R}_n \stackrel{\text{def}}{=} \frac{1}{n} \sum_{t=1}^n (\mathbf{x}_t - \mathbf{m}_n)(\mathbf{x}_t - \mathbf{m}_n)^T$$

in the real case [resp.,

$$\mathbf{R}_n \stackrel{\text{def}}{=} \frac{1}{n} \sum_{t=1}^n (\mathbf{x}_t - \mathbf{m}_n)(\mathbf{x}_t - \mathbf{m}_n)^H$$

in the complex case], where

$$\mathbf{x}_t \stackrel{\text{def}}{=} (x_t, x_{t-1}, \dots, x_{t-p+1})^T$$

and

$$\mathbf{m}_n \stackrel{\text{def}}{=} (m_n, \dots, m_n)^T.$$

The asymptotic normality of the sample mean  $m_n$  and sample covariance matrix  $\mathbf{R}_n$  is proved in Section II. As an application of this result, the asymptotic normal distribution of any sinusoidal frequencies estimator of such time series, based on second-order statistics, is derived in Section III.

### II. CENTRAL LIMIT THEOREMS

For the convenience of the reader, the definition of the complex Gaussian distribution is recalled. A complex random  $p \times 1$  vector  $\mathbf{y}$  has a zero-mean complex Gaussian distribution specified by a  $p \times p$  positive-definite matrix  $\Sigma_1$  and a  $p \times p$  symmetric matrix  $\Sigma_2$  and denoted  $\mathcal{N}(\mathbf{0}; \Sigma_1, \Sigma_2)$ <sup>4</sup> if the  $2p$ -joint distribution of the real and imaginary part of  $\mathbf{y}$  is  $2p$ -zero-mean real Gaussian, i.e., if for any complex  $p \times 1$  vector  $\mathbf{w}$ , the real scalar  $\mathbf{w}^H \mathbf{y} + (\mathbf{w}^H \mathbf{y})^H$  has a zero-mean real Gaussian distribution with variance

$$2\mathbf{w}^H \Sigma_1 \mathbf{w} + \mathbf{w}^H \Sigma_2 \mathbf{w}^* + \mathbf{w}^T \Sigma_2^* \mathbf{w} \quad (2.1)$$

where  $E(\mathbf{y}\mathbf{y}^H) = \Sigma_1$  and  $E(\mathbf{y}\mathbf{y}^T) = \Sigma_2$ .

Considering the sample mean, the following theorem is proved in the Appendix.

**Theorem 1:**  $\sqrt{n}(m_n - m)$  converges in distribution to the zero-mean real [resp., complex] Gaussian distribution of variance  $c_m$  [resp.,  $c_m, c'_m$ ] in the real case [resp., in the complex case] irrespective of the phase model

$$\sqrt{n}(m_n - m) \xrightarrow{\mathcal{L}} \mathcal{N}(0, c_m) \quad [\text{resp., } \mathcal{N}(0; c_m, c'_m)]. \quad (2.2)$$

<sup>2</sup>Here, circular refers to second-order circular (see, e.g., [6], which is sometimes called “proper” (see [7])).

<sup>3</sup>In this model,  $f_k \neq 0$ , otherwise,  $m$  would be a special case of a sinusoid.

<sup>4</sup>This notation was introduced in [6]. The matrix  $\Sigma_2$  is called relation matrix in [6] and pseudocovariance matrix in [7].

Furthermore,

$$\lim_{n \rightarrow \infty} E(m_n) = m \quad \text{and} \quad \lim_{n \rightarrow \infty} n \text{Var}(m_n) = c_m \quad (2.3)$$

where  $c_m$  and  $c'_m$  are defined as

$$c_m = c_u \left| \sum_{q=0}^Q b_q \right|^2 \quad \text{and} \quad c'_m = c'_u \left( \sum_{q=0}^Q b_q \right)^2. \quad (2.4)$$

Then, considering the sample covariance matrix, if  $\mathbf{R}$  denotes, respectively,  $E[(\mathbf{x}_t - \mathbf{m})(\mathbf{x}_t - \mathbf{m})^T]$  and  $E[(\mathbf{x}_t - \mathbf{m})(\mathbf{x}_t - \mathbf{m})^H]$  in the real and the complex case of the first statistical model with  $\mathbf{m} \stackrel{\text{def}}{=} (m, \dots, m)^T$ , the following theorem is proved in the Appendix.

*Theorem 2:*  $\sqrt{n}(\text{Vec}(\mathbf{R}_n) - \text{Vec}(\mathbf{R}))^5$  converges in distribution to the zero-mean real [resp., complex] Gaussian distribution of covariance  $\mathbf{C}_R$  [resp.,  $\mathbf{C}_R, \mathbf{C}_R \mathbf{K}$ ] in the real case [resp., in the complex case], irrespective of the phase model.

$$\sqrt{n}(\text{Vec}(\mathbf{R}_n) - \text{Vec}(\mathbf{R})) \xrightarrow{L} \mathcal{N}(\mathbf{0}, \mathbf{C}_R) \quad [\text{resp.}, \mathcal{N}(\mathbf{0}, \mathbf{C}_R, \mathbf{C}_R \mathbf{K})]. \quad (2.5)$$

Furthermore,

$$\lim_{n \rightarrow \infty} E(\mathbf{R}_n) = \mathbf{R} \quad \text{and} \quad \lim_{n \rightarrow \infty} n \text{Cov}(\text{Vec}(\mathbf{R}_n)) = \mathbf{C}_R \quad (2.6)$$

where  $\mathbf{C}_R$  is defined respectively in the real and the complex cases as

$$\begin{aligned} \mathbf{C}_R = & \int_{-1/2}^{+1/2} S_v^2(f) \\ & \cdot \left[ \mathbf{e}(f) \mathbf{e}^H(f) \otimes_c \mathbf{e}(f) \mathbf{e}^H(f) + \mathbf{e}(f) \mathbf{e}^T(f) \otimes_c \mathbf{e}(f) \mathbf{e}^T(f) \right] df \\ & + \kappa_u \text{Vec}(\mathbf{B} \mathbf{B}^T) \text{Vec}^T(\mathbf{B} \mathbf{B}^T) \\ & + \frac{1}{2} \sum_{k=1}^K a_k^2 S_v(f_k) \left[ \mathbf{e}(f_k) \mathbf{e}^H(f_k) \otimes_c \mathbf{e}(f_k) \mathbf{e}^H(f_k) \right. \\ & \quad \left. + \mathbf{e}(-f_k) \mathbf{e}^H(-f_k) \otimes_c \mathbf{e}(-f_k) \mathbf{e}^H(-f_k) \right] \\ & + \frac{1}{2} \sum_{k=1}^K a_k^2 S_v(f_k) \left[ \mathbf{e}(f_k) \mathbf{e}^H(-f_k) \otimes_c \mathbf{e}(f_k) \mathbf{e}^H(-f_k) \right. \\ & \quad \left. + \mathbf{e}(-f_k) \mathbf{e}^H(f_k) \otimes_c \mathbf{e}(-f_k) \mathbf{e}^H(f_k) \right] \end{aligned} \quad (2.7)$$

$$\begin{aligned} \mathbf{C}_R = & \int_{-1/2}^{+1/2} S_v^2(f) \left[ \mathbf{e}(f) \mathbf{e}^H(f) \otimes_c \mathbf{e}(f) \mathbf{e}^H(f) \right] df \\ & + \int_{-1/2}^{+1/2} S_v'^2(f) \left[ \mathbf{e}(f) \mathbf{e}^T(f) \otimes_c \mathbf{e}(f) \mathbf{e}^T(f) \right] df \\ & + 2 \sum_{k=1}^K a_k^2 S_v(f_k) \left[ \mathbf{e}(f_k) \mathbf{e}^H(f_k) \otimes_c \mathbf{e}(f_k) \mathbf{e}^H(f_k) \right] \\ & + \kappa_u \text{Vec}(\mathbf{B} \mathbf{B}^H) \text{Vec}^H(\mathbf{B} \mathbf{B}^H) \end{aligned} \quad (2.8)$$

with

$$\mathbf{e}(f) \stackrel{\text{def}}{=} (1, e^{i2\pi f}, \dots, e^{i2(p-1)\pi f})^H$$

where  $\otimes_c$  denotes the complex Kronecker product  $\mathbf{A} \otimes_c \mathbf{B}$ , i.e., the block matrix, the  $(i, j)$  block element of which is  $b_{i,j}^* \mathbf{A}$  and  $\mathbf{K}$  is the

<sup>5</sup>Vec(.) is the “vectorization” operator that turns a matrix into a vector consisting of the columns of the matrix stacked one below another.

<sup>6</sup>This slightly unusual convention makes it easier to deal with complex matrices.

vec-permutation matrix which transforms  $\text{Vec}(\mathbf{A})$  to  $\text{Vec}(\mathbf{A}^T)$  for any square matrix  $\mathbf{A}$ .

$$S_v(f) \stackrel{\text{def}}{=} c_u \left| \sum_{q=0}^Q b_q e^{-i2\pi f q} \right|^2$$

i.e., the spectral density of  $v_t$  and

$$S'_v(f) \stackrel{\text{def}}{=} |c'_u| \left| \left( \sum_{q=0}^Q b_q e^{-i2\pi f q} \right) \left( \sum_{q=0}^Q b_q e^{+i2\pi f q} \right) \right|.$$

$\mathbf{B}$  denotes the  $p \times (p + Q)$  filtering matrix

$$\begin{pmatrix} b_0 & b_1 & \cdots & b_Q \\ & \ddots & & \ddots \\ & & b_0 & b_1 & \cdots & b_Q \end{pmatrix}.$$

*Remark 1:* In (2.6),  $\text{Cov}(\text{Vec}(\mathbf{R}_n))$  denotes

$$E(\text{Vec}(\mathbf{R}_n - \mathbf{R}) \text{Vec}^H(\mathbf{R}_n - \mathbf{R})).$$

We note that

$$\text{Vec}^T(\mathbf{R}_n - \mathbf{R}) = \text{Vec}^H(\mathbf{R}_n - \mathbf{R}) \mathbf{K} \quad (2.9)$$

so

$$E(\text{Vec}(\mathbf{R}_n - \mathbf{R}) \text{Vec}^T(\mathbf{R}_n - \mathbf{R})) = E(\text{Vec}(\mathbf{R}_n - \mathbf{R}) \text{Vec}^H(\mathbf{R}_n - \mathbf{R})) \mathbf{K}.$$

Therefore, the noncircular complex Gaussian asymptotic distribution of  $\mathbf{R}_n$  is characterized by  $\mathbf{C}_R$  only.

*Remark 2:* We note that expression (2.7) of  $\mathbf{C}_R$  obtained in the real case cannot be deduced from expression (2.8) in the complex case as suggested by the Euler relation applied to relation (1.1)

$$a_k \cos(2\pi f_k t + \phi_k) = \frac{a_k}{2} e^{i\phi_k} e^{i2\pi f_k t} + \frac{a_k}{2} e^{-i\phi_k} e^{-i2\pi f_k t}.$$

In fact, if  $S'_v(f)$ ,  $\mathbf{B}^H$ , and  $a_k^2 [\mathbf{e}(f_k) \mathbf{e}^H(f_k) \otimes_c \mathbf{e}(f_k) \mathbf{e}^H(f_k)]$  are, respectively, replaced with  $S_v(f)$ ,  $\mathbf{B}^T$ , and

$$\begin{aligned} & \left( \frac{a_k}{2} \right)^2 [\mathbf{e}(f_k) \mathbf{e}^H(f_k) \otimes_c \mathbf{e}(f_k) \mathbf{e}^H(f_k)] \\ & + \left( \frac{a_k}{2} \right)^2 [\mathbf{e}(-f_k) \mathbf{e}^H(-f_k) \otimes_c \mathbf{e}(-f_k) \mathbf{e}^H(-f_k)] \end{aligned}$$

an extra cross-term appears in (2.7). This surprising property is apparently contradictory, given the result that the asymptotic distribution of the sample covariance matrix does not depend on the phase model. In fact, the explanation comes from certain expressions proved in the complex case in the Appendix (see footnote 10) being valid only if no frequencies are opposite. The fact that  $\phi_k$  and  $-\phi_k$ , associated with  $f_k$  and  $-f_k$ , are not independent is irrelevant.

*Remark 3:* We note that for a “very narrow band” (i.e., the bandwidth is very small with respect to the sampling frequency) moving average (MA) processes  $v_t$ , (2.7) and (2.8) are unbounded. For example, when  $v_t$  tends to be white in  $[f_0 - b, f_0 + b]$  with finite fixed power  $c_v$ , (2.7) and (2.8) are not bounded with  $b$ , because  $S_v(f)$  tends to  $c_v/2b$  for  $|f - f_0| \leq b$  and 0 elsewhere, which implies that  $\mathbf{C}_R$  contains the terms  $\int_{-1/2}^{+1/2} S_v^2(f) df$  which tends to  $\frac{c_v^2}{2b}$ .

Since the matrix  $\mathbf{R}$  is Toeplitz, the “accuracy” of its sample covariance estimate  $\mathbf{R}_n$ , which is non-Toeplitz, should be improved by replacing it by its “Toeplitzed” estimate. This “Toeplitzation,” also known as redundancy averaging in statistical signal and array processing applications [9], is carried out by averaging along the diagonals. The resulting estimate  $\mathbf{R}_n^{\text{to}}$  is referred as the “Toeplitzed” estimated covariance matrix. Because this “Toeplitzation” operates a linear transform on  $\mathbf{R}_n$ , Theorem 2 extends as follows.

*Corollary 1:*  $\text{Vec}(\mathbf{R}_n)$  and  $\text{Vec}(\mathbf{R}_n^{\text{to}})$  have the same asymptotic Gaussian distribution. It is characterized by the asymptotic distribution of the first column  $\mathbf{r}_n$  of  $\mathbf{R}_n$ . In the real case [resp., in the complex case], we have

$$\sqrt{n}(\mathbf{r}_n - \mathbf{r}) \xrightarrow{\mathcal{L}} \mathcal{N}(\mathbf{0}, \mathbf{C}_r) \quad [\text{resp., } \mathcal{N}(\mathbf{0}; \mathbf{C}_r, \mathbf{C}'_r)]. \quad (2.10)$$

Furthermore,

$$\lim_{n \rightarrow \infty} \mathbb{E}(\mathbf{r}_n) = \mathbf{r} \quad \text{and} \quad \lim_{n \rightarrow \infty} n\mathbb{E}[(\mathbf{r}_n - \mathbf{r})(\mathbf{r}_n - \mathbf{r})^T] = \mathbf{C}_r \quad (2.11)$$

resp.,  $\lim_{n \rightarrow \infty} n\mathbb{E}[(\mathbf{r}_n - \mathbf{r})(\mathbf{r}_n - \mathbf{r})^H] = \mathbf{C}_r$

$$\lim_{n \rightarrow \infty} n\mathbb{E}[(\mathbf{r}_n - \mathbf{r})(\mathbf{r}_n - \mathbf{r})^T] = \mathbf{C}'_r \quad (2.12)$$

where  $\mathbf{C}_r$  [resp.,  $\mathbf{C}_r, \mathbf{C}'_r$ ] is defined in the real [resp., complex] case as

$$\begin{aligned} \mathbf{C}_r &= \int_{-1/2}^{+1/2} S_v^2(f) \left[ \mathbf{e}(f)\mathbf{e}^H(f) + \mathbf{e}(f)\mathbf{e}^T(f) \right] df \\ &\quad + \kappa_u \mathbf{B}\mathbf{b}\mathbf{b}^T \mathbf{B}^T + \frac{1}{2} \sum_{k=1}^K a_k^2 S_v(f_k) \\ &\quad \cdot \left[ \mathbf{e}(f_k)\mathbf{e}^H(f_k) + \mathbf{e}(-f_k)\mathbf{e}^H(-f_k) \right. \\ &\quad \left. + \mathbf{e}(f_k)\mathbf{e}^H(-f_k) + \mathbf{e}(-f_k)\mathbf{e}^H(f_k) \right] \end{aligned} \quad (2.13)$$

$$\begin{aligned} \mathbf{C}_r &= \int_{-1/2}^{+1/2} \left[ S_v^2(f)\mathbf{e}(f)\mathbf{e}^H(f) + S_v'^2(f)\mathbf{e}(f)\mathbf{e}^T(f) \right] df \\ &\quad + \kappa_u \mathbf{B}\mathbf{b}\mathbf{b}^H \mathbf{B}^H + 2 \sum_{k=1}^K a_k^2 S_v(f_k)\mathbf{e}(f_k)\mathbf{e}^H(f_k) \end{aligned} \quad (2.14)$$

$$\begin{aligned} \mathbf{C}'_r &= \int_{-1/2}^{+1/2} \left[ S_v^2(f)\mathbf{e}(f)\mathbf{e}^T(f) + S_v'^2(f)\mathbf{e}(f)\mathbf{e}^H(f) \right] df \\ &\quad + \kappa_u \mathbf{B}\mathbf{b}^* \mathbf{b}^H \mathbf{B}^T + 2 \sum_{k=1}^K a_k^2 S_v(f_k)\mathbf{e}(f_k)\mathbf{e}^T(f_k) \end{aligned} \quad (2.15)$$

with  $\mathbf{b}$  is the  $(p+Q) \times 1$  vector  $(b_0, \dots, b_Q, 0, \dots, 0)^T$ .

*Remark 3:* In the complex case, we note that contrary to  $\mathbf{R}_n$  (see Remark 1), the asymptotic distribution of  $\mathbf{r}_n$  is not characterized by  $\mathbf{C}_r$  only.

Relation (2.11) reads componentwise with  $\mathbf{r}_n \stackrel{\text{def}}{=} (r_n^0, \dots, r_n^{p-1})^T$  and

$$r_b^i \stackrel{\text{def}}{=} \begin{cases} b_0 b_i + \dots + b_{Q-i} b_Q, & \text{for } 0 \leq i \leq Q \\ 0, & \text{for } Q < i \leq p-1 \end{cases}$$

$$\begin{aligned} &\lim_{n \rightarrow \infty} n\text{Cov}(r_n^i, r_n^j) \\ &= 2 \int_{-1/2}^{+1/2} S_v^2(f) \cos(2\pi i f) \cos(2\pi j f) df \\ &\quad + 2 \sum_{k=1}^K a_k^2 S_v^2(f_k) \cos(2\pi i f_k) \cos(2\pi j f_k) + \kappa_u r_b^i r_b^j, \quad i, j \geq 0. \end{aligned}$$

This extends the property given by [10] and by [3, Theorem 9.4] where  $v_t$  is, respectively, a sequence of i.i.d. zero-mean random variables with  $\mathbb{E}(v_t^4) < \infty$  or a sequence of i.i.d. Gaussian distributed zero-mean random variables.

### III. APPLICATION TO ESTIMATION OF SINUSOIDAL FREQUENCIES

Theorem 2 allows us to derive the asymptotic performance of most covariance-based sinusoidal frequencies estimation algorithms. With this aim, we adopt a functional analysis approach which consists in

recognizing that the whole process of constructing an estimate  $\mathbf{f}_n$  of  $\mathbf{f} \stackrel{\text{def}}{=} (f_1, \dots, f_K)^T$  is equivalent to defining a functional relationship linking this estimate  $\mathbf{f}_n$  to the statistics  $\mathbf{R}_n$  from which it is inferred. This functional dependence is denoted  $\mathbf{f}_n = \text{alg}(\mathbf{R}_n)$ . Clearly,  $\mathbf{f} = \text{alg}(\mathbf{R})$  with  $\mathbf{R} = \mathbf{E}(\mathbf{f})\mathbf{\Delta}\mathbf{E}^H(\mathbf{f}) + c_u \mathbf{B}\mathbf{B}^H$ ,<sup>7</sup> where

$$\mathbf{E}(\mathbf{f}) \stackrel{\text{def}}{=} (\mathbf{e}(f_1), \dots, \mathbf{e}(f_K))$$

and

$$\mathbf{\Delta} \stackrel{\text{def}}{=} \text{Diag}(a_1^2, \dots, a_K^2).$$

So the different algorithms  $\text{alg}(\cdot)$  constitute distinct extensions of the mapping  $\mathbf{R} \xrightarrow{\text{alg}} \mathbf{f}$  generated by any unstructured Hermitian matrix  $\mathbf{R}_n$ . In the following, we consider ‘‘regular’’ algorithms. More specifically, we assume the following conditions.

- 1) The function  $\text{alg}(\cdot)$  is differentiable in a neighborhood of  $\mathbf{R}$ , i.e., if  $\mathbf{D}_{f,R}^{\text{alg}}$ <sup>8</sup> denotes the  $K \times p^2$  matrix of this differential evaluated at point  $\mathbf{R}$

$$\text{alg}(\mathbf{R} + \delta\mathbf{R}) = \mathbf{f} + \mathbf{D}_{f,R}^{\text{alg}} \text{Vec}(\delta\mathbf{R}) + o(\delta\mathbf{R}). \quad (3.1)$$

- 2) For any  $\mathbf{f}$ , any positive-definite diagonal matrix  $\mathbf{\Delta}$  and any  $c_u$

$$\text{alg}(\mathbf{E}(\mathbf{f})\mathbf{\Delta}\mathbf{E}^H(\mathbf{f}) + c_u \mathbf{B}\mathbf{B}^H) = \mathbf{f}. \quad (3.2)$$

These two requirements are met for example by the high-resolution second-order frequency estimators such as MUSIC, weighted MUSIC, Min-Norm, TAM, and ESPRIT, which all assume that  $v_t$  is white. With (3.1) and (3.2), the following result is proved in the Appendix.

*Theorem 3:*  $\sqrt{n}(\mathbf{f}_n - \mathbf{f})$  converges in distribution to the zero-mean Gaussian distribution of the covariance  $\mathbf{C}_f$ , which is invariant with respect to the distribution of the noise innovation

$$\sqrt{n}(\mathbf{f}_n - \mathbf{f}) \xrightarrow{\mathcal{L}} \mathcal{N}(\mathbf{0}, \mathbf{C}_f) \quad (3.3)$$

with

$$\begin{aligned} \mathbf{C}_f &= \int_{-1/2}^{+1/2} \mathbf{D}_{f,R}^{\text{alg}} \left[ S_v^2(f)(\mathbf{e}(f)\mathbf{e}^H(f) \otimes_c \mathbf{e}(f)\mathbf{e}^H(f)) \right. \\ &\quad \left. + S_v'^2(f)(\mathbf{e}(f)\mathbf{e}^T(f) \otimes_c \mathbf{e}(f)\mathbf{e}^T(f)) \right] \left( \mathbf{D}_{f,R}^{\text{alg}} \right)^H df. \end{aligned} \quad (3.4)$$

So, although the asymptotic covariance of  $\text{Vec}(\mathbf{R}_n)$  is very sensitive to the distribution of  $u_t$ ,<sup>9</sup> the asymptotic performance of most covariance-based sinusoidal frequency estimators is invariant with respect to the distribution of the noise innovation. However, this asymptotic covariance  $\mathbf{C}_f$  stays unbounded for narrow-band noise of fixed power because of the term  $\int_{-1/2}^{+1/2} S_v^2(f) df$  in (3.4). We note that Theorem 3 extends a result given in [13], where explicit expressions for the covariance of the estimation errors associated with MUSIC and ESPRIT methods are derived for complex circular Gaussian white noise.

In the special case, where the spectral density  $S_v(f)$  is known up to a multiplicative constant, the whitening of the noise used classically in direction of arrival (DOA) estimation (see, e.g., [14]) can be used to

<sup>7</sup>We consider the complex case only, extension to the real case is straightforward.

<sup>8</sup>Expressions of  $\mathbf{D}_{f,R}^{\text{alg}}$  are ordinarily deduced from perturbation calculus (see, e.g., [11] for the standard MUSIC algorithm).

<sup>9</sup> $(n\text{Cov}(\text{Vec}(\mathbf{R}_n)))$  is unbounded for the super-Gaussian case under the constraint of fixed power because of  $\kappa_u$  in (2.7) and (2.8).

advantage. In this approach, after  $v_t$  is whitened by a linear transformation applied to  $\mathbf{x}_t$ , any covariance-based DOA methods based on a calibrated array of generic steering vector in white noise (such as MUSIC, weighted MUSIC, Min-Norm, ...) can be used. In these circumstances, it makes sense to study the influence of the spectrum of  $v_t$  and the selected linear transformation on the performance of this sinusoidal frequency estimator. Considering our functional analysis, Theorem 3 answers this question. The process  $v_t$  is whitened using the Cholesky decomposition  $\mathbf{L}^H \mathbf{L}$  of  $(\mathbf{B}\mathbf{B}^H)^{-1}$  (see, e.g., [15, relation 1.7.19]) and any unitary matrix  $\mathbf{Q}$

$$(\mathbf{B}\mathbf{B}^H)^{-1} = \mathbf{L}'^H \mathbf{L}' \quad \text{with} \quad \mathbf{L}' \stackrel{\text{def}}{=} \mathbf{Q}\mathbf{L}$$

and the covariance matrix of  $\mathbf{x}_t$  becomes

$$\mathbf{R}' = \mathbf{L}' \mathbf{E}(\mathbf{f}) \Delta (\mathbf{L}' \mathbf{E}(\mathbf{f}))^H + c_u \mathbf{I}.$$

If  $\text{alg}(\cdot)$  denotes an algorithm based on generic steering vector and white noise assumption, the sinusoidal frequencies are estimated through the following scheme:

$$\mathbf{R}_n \mapsto \mathbf{R}'_n \stackrel{\text{def}}{=} \mathbf{L}' \mathbf{R}_n \mathbf{L}'^H \stackrel{\text{alg}}{\mapsto} \mathbf{f}_n \Rightarrow \mathbf{R}_n \stackrel{\text{alg}}{\mapsto} \mathbf{f}_n.$$

Applying the chain differential rule, Theorem 3 applies in this situation by replacing in (3.4),  $\mathbf{D}_{f,R}^{\text{alg}}$  by  $\mathbf{D}'_{f,R} = \mathbf{D}_{f,R'}^{\text{alg}} (\mathbf{L}' \otimes_c \mathbf{L}')$ , because  $\text{Vec}(\mathbf{R}'_n) = (\mathbf{L}' \otimes_c \mathbf{L}') \text{Vec}(\mathbf{R}_n)$ .

#### APPENDIX PROOF OF THEOREMS

The complex case is considered only as the same approach may be used for the real case.

##### A. Proof of Theorem 1

First of all,  $\sqrt{n}(m_n - m)$  is decomposed as

$$\sqrt{n}(m_n - m) = \sum_{k=1}^K a_k e^{i\phi_k} \frac{1}{\sqrt{n}} \left( \sum_{t=1}^n e^{i2\pi f_k t} \right) + \frac{1}{\sqrt{n}} \sum_{t=1}^n v_t. \quad (\text{A1})$$

Because

$$\left| \sum_{t=1}^n e^{i2\pi f_k t} \right| = \left| \frac{\sin \pi n f_k}{\sin \pi f_k} \right|$$

is bounded, the first term of (A1) converges almost surely to 0 when  $n \rightarrow \infty$  whatever the phase model. Thus, we can consider the term  $\frac{1}{\sqrt{n}} \sum_{t=1}^n v_t$  only, in the study of the convergence in distribution of  $\sqrt{n}(m_n - m)$ . Let

$$y_t \stackrel{\text{def}}{=} w^* v_t + w v_t^*.$$

$y_t$  is a real stationary  $Q$ -dependent sequence of random variables with mean zero and correlation  $\gamma_k$  with

$$\gamma_k = \sum_{q=0}^Q c_u |w|^2 (b_{k+q}^* b_q + b_{k+q} b_q^*) + c'_u w^{*2} b_{k+q} b_q + c''_u w^2 b_{k+q}^* b_q^*.$$

The conditions of [2, Theorem 6.4.2] are fulfilled. Thus,  $\frac{1}{\sqrt{n}} \sum_{t=1}^n y_t$  converges in distribution to the zero-mean real Gaussian distribution of

variance  $c_y = \gamma_0 + 2 \sum_{q=1}^Q \gamma_q$  and  $\lim_{n \rightarrow \infty} n \text{Var}(\frac{1}{n} \sum_{t=1}^n y_t) = c_y$  with

$$c_y = 2|w|^2 c_u \left| \sum_{q=0}^Q b_q \right|^2 + w^{*2} c'_u \left( \sum_{q=0}^Q b_q \right)^2 + w^2 c''_u \left( \sum_{q=0}^Q b_q^* \right)^2.$$

The theorem follows thanks to (2.1).  $\square$

##### B. Proof of Theorem 2

Because  $\frac{1}{n} \sum_{t=1}^n v_t$  converges in probability to 0 (see, e.g., [2, Proposition 6.3.10]),  $\mathbf{m}_n$  converges in probability to  $\mathbf{m}$ . Using a classical result (e.g., deduced from [2, Propositions 6.3.4 and 6.3.7]), we can deduce that studying the asymptotic distribution of  $\mathbf{R}_n$ , boils down to studying the asymptotic distribution of

$$\mathbf{R}'_n \stackrel{\text{def}}{=} \frac{1}{n} \sum_{t=1}^n (\mathbf{x}_t - \mathbf{m})(\mathbf{x}_t - \mathbf{m})^H.$$

Then, using  $\text{Vec}(\mathbf{a}\mathbf{b}^H) = \mathbf{a} \otimes_c \mathbf{b}$ ,  $\text{Vec}(\mathbf{R}'_n - \mathbf{R})$  is decomposed as

$$\text{Vec}(\mathbf{R}'_n - \mathbf{R}) = \frac{1}{n} \sum_{t=1}^n (\mathbf{z}_t^1 + \mathbf{z}_t^2)$$

with

$$\mathbf{z}_t^1 \stackrel{\text{def}}{=} \mathbf{c}_t \otimes_c \mathbf{v}_t + \mathbf{v}_t \otimes_c \mathbf{c}_t + \mathbf{v}_t \otimes_c \mathbf{v}_t - \text{Vec}(\mathbf{R}_v)$$

and

$$\mathbf{z}_t^2 \stackrel{\text{def}}{=} \sum_{1 \leq k \neq k' \leq K} a_k a_{k'} e^{i(\phi_k - \phi_{k'})} e^{i2\pi(f_k - f_{k'})t} \mathbf{e}(f_k) \otimes_c \mathbf{e}(f_{k'})$$

where

$$\mathbf{c}_t \stackrel{\text{def}}{=} \sum_{k=1}^K a_k e^{i\phi_k} e^{i2\pi f_k t} \mathbf{e}(f_k)$$

$$\mathbf{v}_t \stackrel{\text{def}}{=} (v_t, v_{t-1}, \dots, v_{t-p+1})^T$$

and

$$\mathbf{R}_v \stackrel{\text{def}}{=} \mathbf{E}(\mathbf{v}_t \mathbf{v}_t^H).$$

Because

$$\begin{aligned} & \left\| \sqrt{\frac{1}{n}} \sum_{t=1}^n \mathbf{z}_t^2 \right\| \\ & \leq \frac{1}{\sqrt{n}} \sum_{1 \leq k \neq k' \leq K} a_k a_{k'} \left| \frac{\sin(\pi n(f_k - f_{k'}))}{\sin(\pi(f_k - f_{k'}))} \right| \|\mathbf{e}(f_k) \otimes_c \mathbf{e}(f_{k'})\| \end{aligned}$$

$\sqrt{\frac{1}{n}} \sum_{t=1}^n \mathbf{z}_t^2$  converges almost surely to  $\mathbf{0}$  when  $n \rightarrow \infty$ . Thus, we can consider the term  $\frac{1}{\sqrt{n}} \sum_{t=1}^n \mathbf{z}_t^1$  alone, in the study of the convergence in distribution of  $\frac{1}{\sqrt{n}} \text{Vec}(\mathbf{R}'_n - \mathbf{R})$ . To prove the convergence in distribution of  $\frac{1}{\sqrt{n}} \sum_{t=1}^n \mathbf{z}_t^1$  to a zero-mean noncircular complex Gaussian distribution, we consider the associated scalar real random variable  $y_t \stackrel{\text{def}}{=} \mathbf{w}^H \mathbf{z}_t^1 + (\mathbf{w}^H \mathbf{z}_t^1)^H$  (see definition in Section II). The conditional distribution of  $(y_t)_{t=1, \dots, n}$  given the phases  $(\phi_k)_{k=1, \dots, K}$  is a zero-mean real distribution of  $L$ -dependent (with  $L = p + Q$ ) but not strictly stationary random variables because  $y_t$  are not identically distributed. As such, the conditions of [2, Theorem 6.4.2] are no longer fully satisfied.

To prove Theorem 2, we continue to make use of [2, Theorem 6.4.2] by some modifications of its proof. Following this proof, we must con-

sider first, the limit of  $n\text{Var}(\frac{1}{n} \sum_{t=1}^n y_t / \phi)$  when  $n \rightarrow \infty$ . Thanks to (2.9), this expression may be written as

$$2\mathbf{w}^H \left[ \frac{1}{n} \sum_{1 \leq s, t \leq n} E(\mathbf{z}_s^1 \mathbf{z}_t^{1H} / \phi) \right] \mathbf{w} + \mathbf{w}^H \left[ \frac{1}{n} \sum_{1 \leq s, t \leq n} E(\mathbf{z}_s^1 \mathbf{z}_t^{1H} / \phi) \right] \mathbf{K} \mathbf{w}^* + \mathbf{w}^T \left[ \frac{1}{n} \sum_{1 \leq s, t \leq n} E(\mathbf{z}_s^1 \mathbf{z}_t^{1H} / \phi) \right]^* \mathbf{K} \mathbf{w} \quad (\text{A2})$$

where

$$\frac{1}{n} \sum_{1 \leq s, t \leq n} E(\mathbf{z}_s^1 \mathbf{z}_t^{1H} / \phi) = \mathbf{T}_a + \mathbf{T}_b + \mathbf{T}_c$$

with

$$\begin{aligned} \mathbf{T}_a &\stackrel{\text{def}}{=} \frac{1}{n} \sum_{1 \leq s, t \leq n} E((\mathbf{v}_s \otimes_c \mathbf{c}_s)(\mathbf{c}_t^H \otimes_c \mathbf{v}_t^H) / \phi) \\ &\quad + E((\mathbf{c}_s \otimes_c \mathbf{v}_s)(\mathbf{v}_t^H \otimes_c \mathbf{c}_t^H) / \phi) \\ \mathbf{T}_b &\stackrel{\text{def}}{=} \frac{1}{n} \sum_{1 \leq s, t \leq n} E((\mathbf{v}_s \otimes_c \mathbf{c}_s)(\mathbf{v}_t^H \otimes_c \mathbf{c}_t^H) / \phi) \\ &\quad + E((\mathbf{c}_s \otimes_c \mathbf{v}_s)(\mathbf{c}_t^H \otimes_c \mathbf{v}_t^H) / \phi) \\ \mathbf{T}_c &\stackrel{\text{def}}{=} \frac{1}{n} \sum_{1 \leq s, t \leq n} E((\mathbf{v}_s \otimes_c \mathbf{v}_s - \text{Vec}(\mathbf{R}_v)(\mathbf{v}_t \otimes_c \mathbf{v}_t - \text{Vec}(\mathbf{R}_v))^H). \end{aligned}$$

Thanks to the following property of the vec-permutation matrix  $\mathbf{K}$

$$(\mathbf{a}^H \otimes_c \mathbf{b}^H) \mathbf{K} = \mathbf{b}^T \otimes_c \mathbf{a}^T \quad (\text{A3})$$

$$E((\mathbf{v}_s \otimes_c \mathbf{c}_s)(\mathbf{c}_t^H \otimes_c \mathbf{v}_t^H) / \phi) + E((\mathbf{c}_s \otimes_c \mathbf{v}_s)(\mathbf{v}_t^H \otimes_c \mathbf{c}_t^H) / \phi) = [(E(\mathbf{v}_s \mathbf{v}_t^T) \otimes_c \mathbf{c}_s \mathbf{c}_t^T) + (\mathbf{c}_s \mathbf{c}_t^T \otimes_c E(\mathbf{v}_s \mathbf{v}_t^T))] \mathbf{K}$$

thus the first term of  $\mathbf{T}_a$  becomes

$$\begin{aligned} &\sum_{l=-p-Q+1}^{p+Q-1} \mathbf{R}'_v(l) \otimes_c \\ &\cdot \left( \sum_{1 \leq k, k' \leq K} a_k a_{k'} e^{i(\phi_k + \phi_{k'})} e^{-i2\pi f_{k'} l} \right. \\ &\cdot \left. \left[ \frac{1}{n} \sum_{s \in S_{n,l}} e^{i2\pi(f_k + f_{k'})s} \right] \mathbf{e}(f_k) \mathbf{e}^T(f_{k'}) \right) \mathbf{K} \end{aligned}$$

with  $\mathbf{R}'_v(l) \stackrel{\text{def}}{=} E(\mathbf{v}_s \mathbf{v}_{s-l}^T)$  and  $S_{n,l}$  is the set  $\{s, 1 \leq s \leq n-l \text{ for } l \geq 0 \text{ or } -l+1 \leq s \leq n \text{ for } l \leq 0\}$ . Because<sup>10</sup>

$$\lim_{n \rightarrow \infty} \left| \frac{1}{n} \sum_{s \in S_{n,l}} e^{i2\pi(f_k + f_{k'})s} \right| = 0$$

the first term of  $\mathbf{T}_a$  and, therefore, the term  $\mathbf{T}_a$  tends to  $\mathbf{O}$  when  $n \rightarrow \infty$ . As

$$E((\mathbf{v}_s \otimes_c \mathbf{c}_s)(\mathbf{v}_t^H \otimes_c \mathbf{c}_t^H) / \phi) + E((\mathbf{c}_s \otimes_c \mathbf{v}_s)(\mathbf{c}_t^H \otimes_c \mathbf{v}_t^H) / \phi) = (E(\mathbf{v}_s \mathbf{v}_t^T) \otimes_c \mathbf{c}_s \mathbf{c}_t^T) + (\mathbf{c}_s \mathbf{c}_t^T \otimes_c E(\mathbf{v}_s \mathbf{v}_t^T))$$

<sup>10</sup>Except for the specific case where two frequencies  $f_k$  are opposite.

the first term of  $\mathbf{T}_b$  becomes:

$$\begin{aligned} &\sum_{l=-p-Q+1}^{p+Q-1} \mathbf{R}_v(l) \otimes_c \\ &\cdot \left( \sum_{1 \leq k, k' \leq K} a_k a_{k'} e^{i(\phi_k - \phi_{k'})} e^{i2\pi f_{k'} l} \right. \\ &\cdot \left. \left[ \frac{1}{n} \sum_{s \in S_{n,l}} e^{i2\pi(f_k - f_{k'})s} \right] \mathbf{e}(f_k) \mathbf{e}^H(f_{k'}) \right) \end{aligned}$$

with  $\mathbf{R}_v(l) \stackrel{\text{def}}{=} E(\mathbf{v}_s \mathbf{v}_{s-l}^H)$ . Because

$$\lim_{n \rightarrow \infty} \left| \frac{1}{n} \sum_{s \in S_{n,l}} e^{i2\pi(f_k - f_{k'})s} \right| = 0$$

for  $f_k \neq f_{k'}$  and 1 for  $f_k = f_{k'}$ , the first term of  $\mathbf{T}_b$  tends to

$$\sum_{1 \leq k \leq K} a_k^2 \left( \sum_{l=-p-Q+1}^{p+Q-1} \mathbf{R}_v(l) \right) e^{-i2\pi f_{k'} l} \otimes_c \mathbf{e}(f_k) \mathbf{e}^H(f_k)$$

when  $n \rightarrow \infty$ . With

$$\left( \sum_{l=-p-Q+1}^{p+Q-1} \mathbf{R}_v(l) \right) e^{-i2\pi f_{k'} l} = S_v(f_k) \mathbf{e}(f_k) \mathbf{e}^H(f_k)$$

the term  $\mathbf{T}_b$  tends to

$$2 \sum_{1 \leq k \leq K} a_k^2 S_v(f_k) [\mathbf{e}(f_k) \mathbf{e}^H(f_k) \otimes_c \mathbf{e}(f_k) \mathbf{e}^H(f_k)]. \quad (\text{A4})$$

Then, because  $\mathbf{v}_t = \mathbf{B} \mathbf{u}_t$  with  $\mathbf{u}_t \stackrel{\text{def}}{=} (u_t, u_{t-1}, \dots, u_{t-p-Q+1})^T$ , the term  $\mathbf{T}_c$  becomes

$$(\mathbf{B} \otimes_c \mathbf{B}) n \text{Cov}(\text{Vec}(\mathbf{R}_n^u)) (\mathbf{B}^H \otimes_c \mathbf{B}^H) \quad (\text{A5})$$

with  $\mathbf{R}_n^u \stackrel{\text{def}}{=} \frac{1}{n} \sum_{t=1}^n \mathbf{u}_t \mathbf{u}_t^H$ .

$$[n \text{Cov}(\text{Vec}(\mathbf{R}_n^u))]_{(j-1)(p+Q)+i, (l-1)(p+Q)+k}$$

then becomes

$$\begin{aligned} &\frac{1}{n} \sum_{1 \leq s, t \leq n} E(u_{s-i+1} u_{s-j+1}^* u_{t-k+1}^* u_{t-l+1}) \\ &\quad - E(u_{s-i+1} u_{s-j+1}^*) E(u_{t-k+1}^* u_{t-l+1}). \quad (\text{A6}) \end{aligned}$$

By the definition of  $\text{Cum}(u_{s-i+1}, u_{s-j+1}^*, u_{t-k+1}^*, u_{t-l+1})$ , (A6) is decomposed as

$$\begin{aligned} &E(u_{s-i+1} u_{t-k+1}^*) E(u_{s-j+1} u_{t-l+1}^*) \\ &\quad + E(u_{s-i+1} u_{t-l+1}) E(u_{s-j+1}^* u_{t-k+1}^*) \\ &\quad + \text{Cum}(u_{s-i+1}, u_{s-j+1}^*, u_{t-k+1}^*, u_{t-l+1}). \end{aligned}$$

These three terms are, respectively, equal to

$$\begin{cases} c_u^2, & \text{for } s-t = i-k = j-l \\ 0, & \text{elsewhere} \\ |c'_u|^2, & \text{for } s-t = i-l = j-k \\ 0, & \text{elsewhere} \\ \kappa_u, & \text{for } i=j, k=l \text{ and } s-t = i-k \\ 0, & \text{elsewhere.} \end{cases}$$

Consequently,

$$\lim_{n \rightarrow \infty} [n \text{Cov}(\text{Vec}(\mathbf{R}_n^u))]_{(j-1)(p+Q)+i, (l-1)(p+Q)+k}$$

is defined and decomposed as

$$\begin{cases} c_u^2, & \text{for } i-k = j-l \\ 0, & \text{elsewhere} \end{cases} + \begin{cases} |c'_u|^2, & \text{for } i-l = j-k \\ 0, & \text{elsewhere} \end{cases} + \begin{cases} \kappa_u, & \text{for } i=j, k=l \\ 0, & \text{elsewhere} \end{cases}$$

whose associated matrix is

$$\begin{aligned} & c_u^2 \int_{-1/2}^{+1/2} [\mathbf{e}(f)\mathbf{e}^H(f) \otimes_c \mathbf{e}(f)\mathbf{e}^H(f)] df \\ & + |c'_u|^2 \int_{-1/2}^{+1/2} [\mathbf{e}(f)\mathbf{e}^H(f) \otimes_c \mathbf{e}(f)\mathbf{e}^H(f)] \mathbf{K} df + \kappa_u \text{Vec}(\mathbf{I})\text{Vec}^T(\mathbf{I}). \end{aligned}$$

Then

$$\begin{aligned} & (\mathbf{B} \otimes_c \mathbf{B}) \left[ \int_{-1/2}^{+1/2} [\mathbf{e}(f)\mathbf{e}^H(f) \otimes_c \mathbf{e}(f)\mathbf{e}^H(f)] df \right] (\mathbf{B}^H \otimes_c \mathbf{B}^H) \\ & = \int_{-1/2}^{+1/2} (\mathbf{B}\mathbf{e}(f)\mathbf{e}^H(f)\mathbf{B}^H) \otimes_c (\mathbf{B}\mathbf{e}(f)\mathbf{e}^H(f)\mathbf{B}^H) df, \\ & (\mathbf{B} \otimes_c \mathbf{B}) \left[ \int_{-1/2}^{+1/2} [\mathbf{e}(f)\mathbf{e}^H(f) \otimes_c \mathbf{e}(f)\mathbf{e}^H(f)] \mathbf{K} df \right] (\mathbf{B}^H \otimes_c \mathbf{B}^H) \\ & = \int_{-1/2}^{+1/2} (\mathbf{B}\mathbf{e}(f)\mathbf{e}^H(f)\mathbf{B}^T) \otimes_c (\mathbf{B}\mathbf{e}(f)\mathbf{e}^H(f)\mathbf{B}^T) df \end{aligned}$$

thanks to (A3) with

$$c_u \mathbf{B}\mathbf{e}(f)\mathbf{e}^H(f)\mathbf{B}^H = S_v(f)\mathbf{e}(f)\mathbf{e}^H(f)$$

and

$$|c'_u| \mathbf{B}\mathbf{e}(f)\mathbf{e}^H(f)\mathbf{B}^T = S'_v(f)\mathbf{e}(f)\mathbf{e}^H(f).$$

And then

$$\begin{aligned} \kappa_u (\mathbf{B} \otimes_c \mathbf{B}) \text{Vec}(\mathbf{I})\text{Vec}^T(\mathbf{I}) (\mathbf{B}^H \otimes_c \mathbf{B}^H) \\ = \kappa_u \text{Vec}(\mathbf{B}\mathbf{B}^H) \text{Vec}^H(\mathbf{B}\mathbf{B}^H) \end{aligned}$$

thanks to  $\text{Vec}(\mathbf{ABC}) = (\mathbf{A} \otimes_c \mathbf{C}^H) \text{Vec}(\mathbf{B})$ . Putting together the limits of term  $\mathbf{T}_b$  and of term  $\mathbf{T}_c$

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{1 \leq s, t \leq n} E(\mathbf{z}_s^1 \mathbf{z}_t^{1H} / \phi)$$

is defined and does not depend on the phases  $\phi_k$ . Thanks to (A2) and (2.1), we get (2.8) irrespective of the phase model.

Then, following the proof of [2, Theorem 6.4.2], the application of the classical central limit (CL) theorem (e.g., [2, Theorem 6.4.1]) to the sum

$$\frac{1}{\sqrt{n}} \sum_{t=1}^r y_{t,k}$$

with  $y_{t,k} \stackrel{\text{def}}{=} y_{(t-1)k+1} + \dots + y_{tk-L}$ , where  $r \stackrel{\text{def}}{=} \lfloor n/k \rfloor$  and  $k$  fixed with  $k > L$  for  $n \rightarrow \infty$  is not valid because  $(y_{t,k})_{t=1, \dots, r}$  are zero-mean independent but not identically distributed random variables. We replace the classical CL theorem by the Lyapunov theorem (see, e.g., [8, p. 371]) by verifying the following Lyapunov's condition [8, Relation (27.16)] with  $\delta = 2$ :

$$\lim_{r \rightarrow \infty} \frac{\sum_{t=1}^r E(y_{t,k}^{2+2} / \phi)}{\left( \sqrt{\sum_{t=1}^r E(y_{t,k}^2 / \phi)} \right)^{2+2}} = 0. \quad (\text{A7})$$

As

$$\frac{1}{n} \sum_{t=1}^r E(y_{t,k}^2 / \phi) = n \text{Var} \left( \frac{1}{n} \sum_{t=1}^r y_{t,k} / \phi \right)$$

we get after similar manipulations as previously that

$$\sum_{t=1}^r E(y_{t,k}^2 / \phi) \propto n, \quad \text{when } n \rightarrow \infty.$$

On the other hand,  $\frac{1}{n} \sum_{t=1}^r E(y_{t,k}^4 / \phi)$  can be decomposed as the sum of terms

$$\begin{aligned} c_{a,b,c,d}(\mathbf{w}) \frac{1}{n} \sum_{t=1}^r \left( \sum_{\substack{1 \leq l, l', l'', l''' \leq k-L}} E((\mathbf{z}_{(t-1)k+l}^1)^{s_a} (\mathbf{z}_{(t-1)k+l'}^1)^{s_b} \right. \\ \left. \cdot (\mathbf{z}_{(t-1)k+l''}^1)^{s_c} (\mathbf{z}_{(t-1)k+l'''}^1)^{s_d} / \phi) \right) \quad (\text{A.8}) \end{aligned}$$

for  $0 \leq a, b, c, d \leq p^2$ , where  $c_{a,b,c,d}(\mathbf{w})$  is an appropriate function of  $\mathbf{w}$  and where  $(\mathbf{y}_{(t-1)k+l}^1)^{s_i}$  denotes the  $i$ th component of  $\mathbf{y}_{(t-1)k+l}^1$  which is conjugated for certain indexes. Because an examination of the term (A8) shows that it has a limit when  $n \rightarrow \infty$ ,

$$\sum_{t=1}^r E(y_{t,k}^4 / \phi) \propto n, \quad \text{when } n \rightarrow \infty.$$

So Lyapounov's condition (A7) with  $\delta = 2$  is proved. Therefore, the conditional real scalar random variable

$$\frac{\sum_{t=1}^r y_{t,k}}{\sqrt{\sum_{t=1}^r E(y_{t,k}^2 / \phi)}}$$

converges in distribution to the zero-mean, unit variance real Gaussian distribution when  $r \rightarrow \infty$ .

Finally, incorporating the other elements of the proof of [2, Theorem 6.4.2],  $\sqrt{n} \frac{1}{n} \sum_{t=1}^n y_t$  converges in distribution to the zero-mean, Gaussian distribution of variance

$$2\mathbf{w}^H \mathbf{C}_R \mathbf{w} + \mathbf{w}^H \mathbf{C}_R \mathbf{K} \mathbf{w}^* + \mathbf{w}^T \mathbf{C}_R^* \mathbf{K} \mathbf{w}$$

with  $\mathbf{C}_R$  given by (2.8). And by application of the Cramer-Wold theorem [8, Theorem 29.4], the complex random vector  $\sqrt{n} \frac{1}{n} \sum_{t=1}^n \mathbf{z}_t^1$  converges in distribution to the zero-mean complex noncircular Gaussian distribution  $\mathcal{N}(\mathbf{0}; \mathbf{C}_R, \mathbf{C}_R \mathbf{K})$ .  $\square$

### C. Proof of Corollary 1

Thanks to the "Toeplitzation" projection matrix  $\mathbf{T}_o$ ,  $\text{Vec}(\mathbf{R}_n^{\text{to}}) = \mathbf{T}_o \text{Vec}(\mathbf{R}_n)$ . Therefore, Theorem 2 extends to  $\mathbf{R}_n^{\text{to}}$  with the asymptotic covariance matrix  $\mathbf{C}_R^{\text{to}} = \mathbf{T}_o \mathbf{C}_R \mathbf{T}_o$ . Because

$$\begin{aligned} & \mathbf{e}(f_k) \mathbf{e}^+(f_l) \otimes_c \mathbf{e}(f_k) \mathbf{e}^+(f_l) \\ & = (\mathbf{e}(f_k) \otimes_c \mathbf{e}(f_k)) (\mathbf{e}^+(f_l) \otimes_c \mathbf{e}^+(f_l)), \quad \text{with } + \stackrel{\text{def}}{=} T \text{ or } H \end{aligned}$$

and  $\mathbf{e}(f_i) \otimes_c \mathbf{e}(f_i) = \text{Vec}(\mathbf{e}(f_i) \mathbf{e}^H(f_i))$  with  $\mathbf{e}(f_i) \mathbf{e}^H(f_i)$  is a Toeplitz matrix

$$\mathbf{T}_o (\mathbf{e}(f_k) \mathbf{e}^+(f_l) \otimes_c \mathbf{e}(f_k) \mathbf{e}^+(f_l)) \mathbf{T}_o = \mathbf{e}(f_k) \mathbf{e}^+(f_l) \otimes_c \mathbf{e}(f_k) \mathbf{e}^+(f_l).$$

Then, because  $\mathbf{B}\mathbf{B}^+$  is also a Toeplitz matrix, the relation  $\mathbf{T}_o \mathbf{C}_R \mathbf{T}_o = \mathbf{C}_R$  is proved. Therefore, the "Toeplitzation" does not improve the covariance estimate and the expressions of  $\mathbf{C}_r$  and  $\mathbf{C}'_r$  are given by the blocks (1, 1) of  $\mathbf{C}_R$  and  $\mathbf{C}'_R$ , respectively.  $\square$

### D. Proof of Theorem 3

From regularity condition (3.1), the asymptotic behaviors of  $\mathbf{f}_n$  and  $\mathbf{R}_n$  are directly related. The standard result on regular functions of asymptotically normal statistics (see, e.g., [12, Theorem, p. 22]) applies. So (3.3) with  $\mathbf{C}_f = \mathbf{D}_{f,R}^{\text{alg}} \mathbf{C}_R (\mathbf{D}_{f,R}^{\text{alg}})^H$ . Furthermore, this closed-form expression simplifies if (1) and (2) are taken into account

$$\begin{aligned} \mathbf{f} &= \text{alg}(\mathbf{E}(\mathbf{f})(\Delta + \delta\Delta)\mathbf{E}^H(\mathbf{f}) + (c_u + \delta c_u)\mathbf{B}\mathbf{B}^H) \\ &= \mathbf{f} + \mathbf{D}_{f,R}^{\text{alg}} \text{Vec}(\mathbf{E}(\mathbf{f})\delta\Delta\mathbf{E}^H(\mathbf{f}) + \delta c_u\mathbf{B}\mathbf{B}^H) + o(\delta\Delta) + o(\delta c_u) \\ &= \mathbf{f} + \mathbf{D}_{f,R}^{\text{alg}} \left( \sum_{k=1}^K \delta a_k^2 (\mathbf{e}(f_k) \otimes_c \mathbf{e}^H(f_k)) + \delta c_u \text{Vec}(\mathbf{B}\mathbf{B}^H) \right) \\ &\quad + o(\delta\Delta) + o(\delta c_u) \end{aligned} \quad (\text{A9})$$

where

$$\text{Vec}(\mathbf{e}(f_k)\mathbf{e}^H(f_k)) = \mathbf{e}(f_k) \otimes_c \mathbf{e}^H(f_k)$$

is used in the third equality. Therefore, the following constraints upon  $\mathbf{D}_{f,R}^{\text{alg}}$  hold:

$$\mathbf{D}_{f,R}^{\text{alg}} [\mathbf{e}(f_k) \otimes_c \mathbf{e}^H(f_k)] = \mathbf{0}, \quad k = 1, \dots, K$$

and  $\mathbf{D}_{f,R}^{\text{alg}} \text{Vec}(\mathbf{B}\mathbf{B}^H) = \mathbf{0}$  (A10)

and using (2.8), the proof follows.  $\square$

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## Generalizing Carathéodory's Uniqueness of Harmonic Parameterization to $N$ Dimensions

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**Abstract**—Consider a sum of  $F$  exponentials in  $N$  dimensions, and let  $I_n$  be the number of equispaced samples taken along the  $n$ th dimension. It is shown that if the frequencies or decays along every dimension are distinct and  $\sum_{n=1}^N I_n \geq 2F + (N - 1)$ , then the parameterization in terms of frequencies, decays, amplitudes, and phases is unique. The result can be viewed as generalizing a classic result of Carathéodory to  $N$  dimensions. The proof relies on a recent result regarding the uniqueness of low-rank decomposition of  $N$ -way arrays.

**Index Terms**—Multidimensional harmonic retrieval, multiway analysis, PARALLEL FACTOR (PARAFAC) analysis, spectral analysis, uniqueness.

### I. INTRODUCTION

The problem of harmonic retrieval and, more generally, exponential retrieval permeates the applied sciences and engineering. Although one-dimensional (1-D) exponential retrieval is most common (e.g., see [17] and references therein), the multidimensional case appears in a variety of important applications like joint azimuth, elevation, delay, and Doppler estimation in antenna array processing for communications [3]–[6], synthetic aperture radar (e.g., [7], [10] and references therein), and also certain signal separation problems in chemistry.

A wide variety of nonparametric and parametric techniques have been developed for the harmonic retrieval problem in one or more dimensions. Underpinning technique and practice of harmonic retrieval is the issue of identifiability, i.e., uniqueness of model parameterization. Owing to the work of Carathéodory [1] and later Pisarenko [11], this issue is well understood for the case of 1-D harmonics. In the case of multidimensional harmonics (and, more generally, exponentials), one can apply the 1-D result separately in each dimension, but this has two serious drawbacks. First, this approach does not reap the benefits of the rich multidimensional structure, leading to uniqueness conditions that are unnecessarily strict. Second, the association problem (i.e., whether the "pairing" of frequencies along different dimensions is unique) remains.

The uniqueness problem is hard for harmonics in two or higher dimensions. Only partial results are known for the two-dimensional (2-D) case [8], [10]. For example, [10] considers one possible formulation of the 2-D harmonic retrieval problem wherein the frequencies are assumed to occur at the intersections of certain unknown grid lines in the 2-D frequency domain, and provides sufficient conditions for identifiability. In the case of a single realization of the 2-D harmonic mixture, the conditions in [10] require that one has sufficiently many samples in each dimension for the 1-D result of Carathéodory to kick in.

The contribution of this correspondence is a general uniqueness result for  $N$ -dimensional exponential mixtures that is valid for any  $N$  and

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